

Connection diagram

The cables coming out of the motors are black. No matter how you connect them to the controller. The direction of rotation will be later determined in the AlexMos GUI.

For the RC data wire, you can choose any free channel. I chose channel 11 (3) for the pitch and channel 10 (2) for the YAW. A detailed explanation on how to configure the receiver is given in the video '3 axis Gimbal 'FC123-002' - part 5'

